Abstract:

Method for Steering a Vehicle with Superimposed Steering

A method of steering a vehicle with a superimposed steering system, wherein a steering angle input by the driver and an additional angle (additional steering angle) is determined and wherein the additional steering angle can override the input steering angle according to further quantities, in particular diving-dynamics quantities, by means of an electric motor, is characterized in that the method includes a steering angle control with a subordinated current or torque control of the electric motor.

(Figure 1)